

Multi-Agent Systems

Biology, Traffic flows, Social dynamics

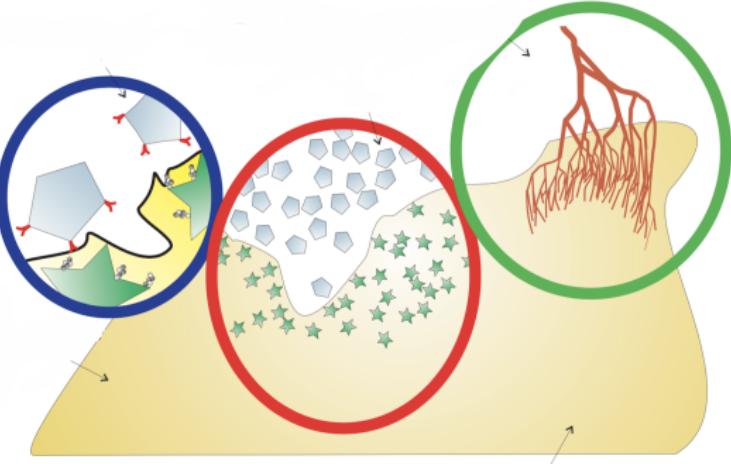
M. Delitala, M. Scianna, A. Tosin

Department of Mathematical Sciences, Politecnico di Torino, Italy

Kick-off meeting T2 - Politecnico di Torino, March, 14th, 2018

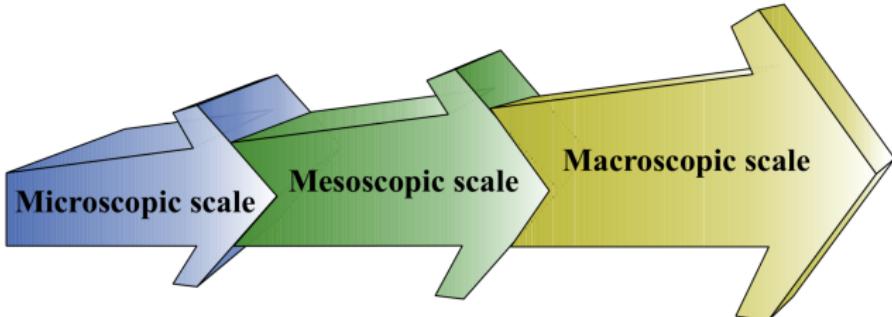
Multiscale modelling

- System biology, ecology of cancer and collective migration
- Multi-level, hybrid and nested models



Delitala, Hillen, Springer, Pro Math Stat, 2014

Scianna, Preziosi, Mult Mod Sim, 2012



Mathematical structures

- Boltzmann-type kinetic equations

$$\partial_t f + v \partial_x f = Q(f, f) + \Gamma(f)f$$

$$Q(f, f) = \iint \left(\frac{1}{|J|} f(v') f(w') - f(v) f(w) \right) dw$$

- Fokker-Planck equations

$$\partial_t f + \partial_v (K(f)f) = \partial_v^2 (D^2(v)f)$$

$$K(f) = \int k(v, w) f(w) dw$$

- Transport of measures

$$\mu_t = \gamma_t \# \mu_0$$

- Reaction-diffusion equations

$$\partial_t u = \nabla \cdot (\mathbf{D} \nabla u) + R(u)$$

- Nested cellular Potts models

$$H = \sum_{celli} (a_i - A_{targ})^2 + H_{surf} + \dots$$

- Conservation/balance laws

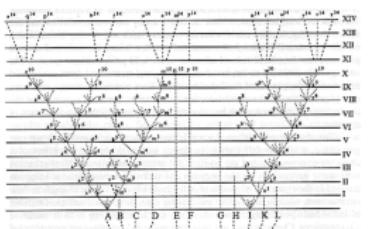
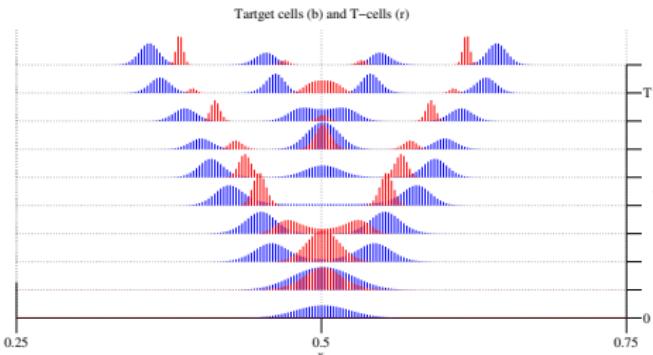
$$\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) = \Gamma(\rho)$$

- Population dynamics

$$\begin{cases} \dot{x} = f(x, y) \\ \dot{y} = g(x, y) \end{cases}$$

Evolutionary dynamics

- Mutation and *selection principle in biology*
- Immune system *learning and immunoediting*



C. Darwin, 1859

- Asymptotic limits
- Structured population with continuous variable

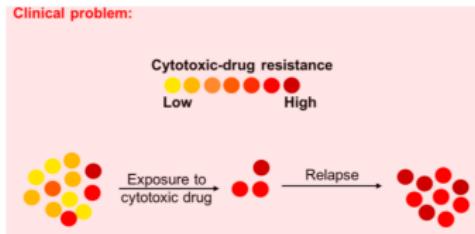
$$\frac{\partial}{\partial t} f_i(t, u) = \underbrace{\sum_{k=1}^2 \int_U A_k^i(u_*, u; \epsilon) f_k(t, u_*) du_*}_{\text{EMT, mutations and renewal}} - f_i(t, u) + \underbrace{\kappa(u) n_3(t) f_i(t, u)}_{\text{cell proliferation}}$$

$$- \underbrace{\mu_i(u) f_i(t, u) (n_1(t) + n_2(t))}_{\text{cell-cell competition}} - \underbrace{\mu^T g_1(t) f_i(t, u)}_{\text{destruction due to CAs}}$$

$$- \underbrace{\mu^T f_i(t, u) \int_V e^{-\theta^T (v^* - u)^2} g_2(t, v^*) dv^*}_{\text{destruction due to TTAs}},$$

Evolutionary dynamics and therapies

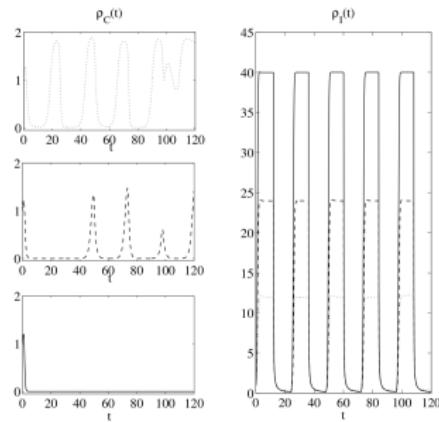
Clinical problem:



- Therapeutic role of external agents: *selection for resistance*.
- Optimization of *immunotherapies*
- IBM and *micro-meso limit*

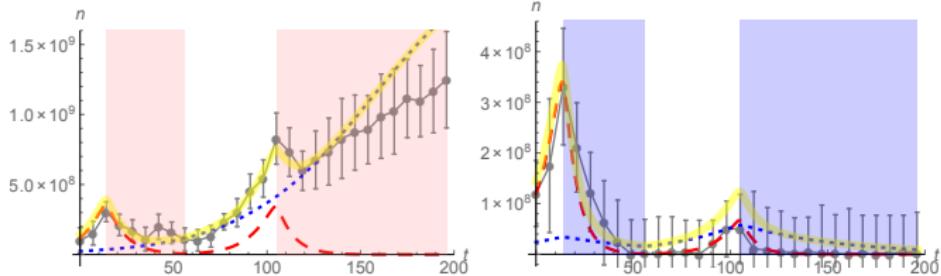
$$\frac{\partial}{\partial t} f_C(t, u) = \underbrace{(\kappa_C - \mu_C \varrho_C(t)) f_C(t, u)}_{\text{cancer growth and cell competition}} - \underbrace{f_C(t, u) \int_V \eta_{\theta_I}(|u - v|) f_I(t, v) dv}_{\text{immune competition}}$$

$$\begin{aligned} \frac{\partial}{\partial t} f_I(t, v) &= \underbrace{\left[\int_U \eta_{\theta_E}(|u - v|) f_C(t, u) du + \kappa_P c_P(t) \right] f_I(t, v)}_{\text{clonal expansion and boosting of T-cell proliferation}} \\ &\quad - \underbrace{\frac{\mu_I}{1 + \mu_M c_M(t)} \varrho_I(t) f_I(t, v)}_{\text{homeostatic regulation and boosting of immune memory}} \end{aligned}$$

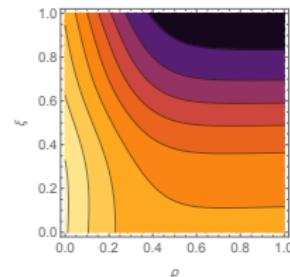


Evolutionary dynamics and drug resistance

- Combination therapies: dose and time protocols
- Population dynamics approach

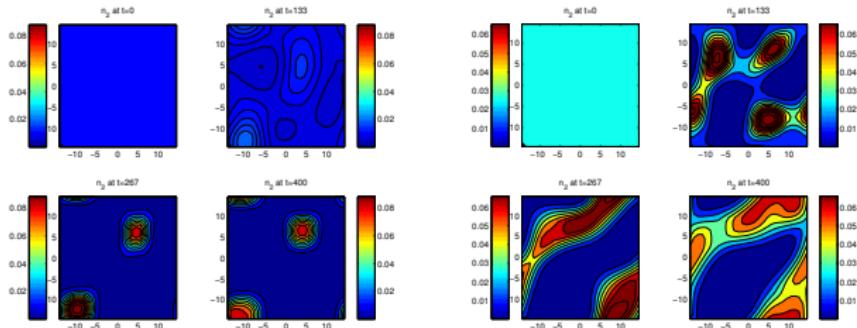


$$\begin{aligned}\frac{dx_1}{dt} &= \underbrace{r_1 x_1 - \frac{r_1}{K_1} x_1^2}_{\text{proliferation}} - \underbrace{\frac{b_{12}}{K_1} x_1 x_2}_{\text{competition}} - \underbrace{\frac{c_1}{K_1} x_1 z}_{\text{predation}} - g_1(t)x_1 - \frac{h(t)}{K_1} x_1 z, \\ \frac{dx_2}{dt} &= r_2 x_2 - \frac{r_2}{K_2} x_2^2 - \frac{b_{21}}{K_2} x_1 x_2 - \frac{c_2}{K_2} x_2 z - g_2(t)x_2 - \frac{h(t)}{K_2} x_2 z, \\ \frac{dz}{dt} &= \underbrace{\beta z \left(1 - \frac{z}{H}\right)}_{\text{proliferation}} + \underbrace{\frac{\alpha_1}{H} x_1 z + \frac{\alpha_2}{H} x_2 z}_{\text{recognition}}.\end{aligned}$$



Tumor microenvironment

- Pattern formation, adhesion and diffusion in *co-culture of epithelial and mesenchymal cells*



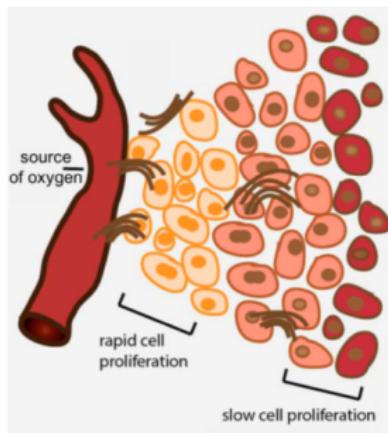
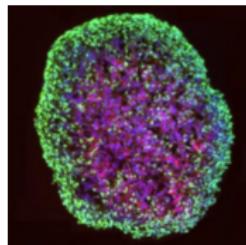
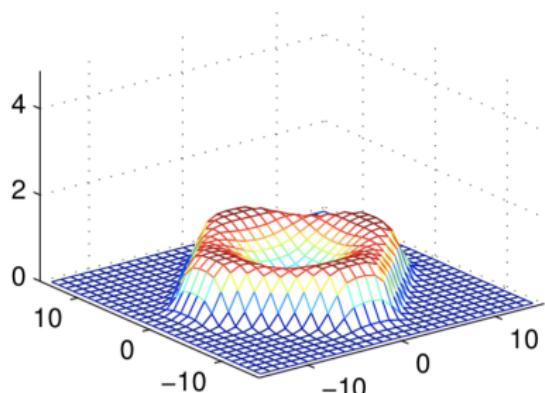
$$\partial_t f_1 + \mathbf{v} \cdot \nabla_{\mathbf{x}} f_1 = \underbrace{\frac{1}{|V|} \left(1 + \frac{\mathbf{v} \cdot \nabla_{\mathbf{x}} n_4}{\beta + |\mathbf{v}| |\nabla_{\mathbf{x}} n_4|} \right) n_1 - f_1}_{\text{random motion and chemotactic reorientation}}$$

+ $\underbrace{\frac{(1-\gamma)}{|V|} n_1 (n_1 + n_3) - (n_1 + n_3) f_1}_{\text{homotypic adhesion}}$

+ $\underbrace{(\kappa - \mu N) f_1}_{\text{proliferation and competition}}$

Evolutionary dynamics and therapies

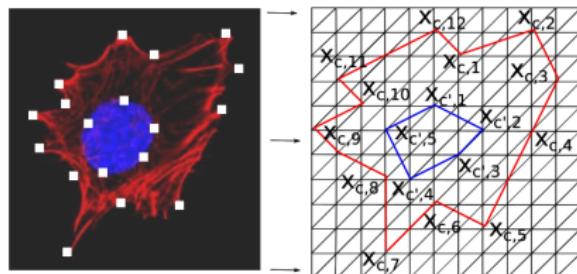
- Tumor micro-environment, hypoxic regions, and *evolutionary niche*.



$$\partial_t n_{20}(t, x) + \nabla_x \cdot (D \nabla_x n_{20}(t, x) - \Gamma[n_{40}] n_{20}(t, x)) = 0$$

Nested Cellular Potts Model

- Interface between different modeling techniques
- Individual/discrete description of cell-level elements:
 - compartmentalized lattice- or vertex-based representation
 - stochastic energy-based laws for cell movement (Metropolis algorithm for Monte Carlo-Boltzmann thermodynamics)
- Continuous representation of molecular elements (RD Eqs.)



$$H(t) = \lambda_a \sum_i (a_i - a_{\text{targ}})^2 + H_{\text{force}}(t) + \dots$$

$$P_{\text{cell movement}}(t) = \min \left\{ e^{-\Delta H/T}, 1 \right\}$$

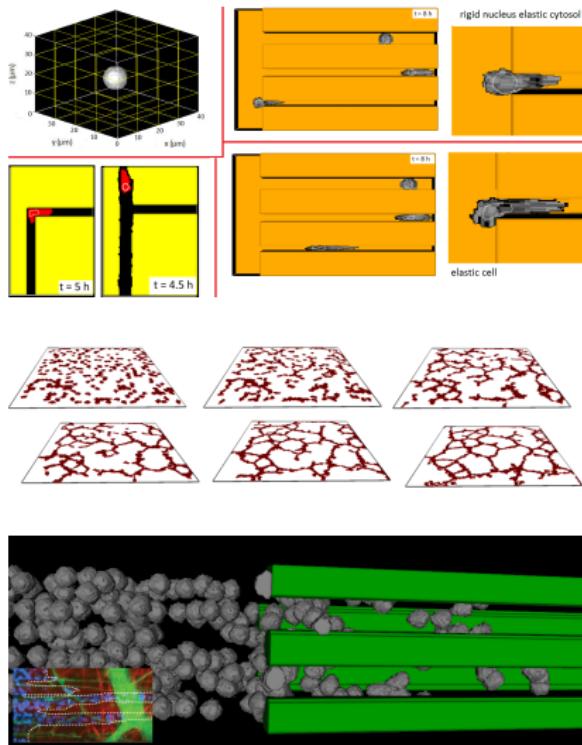
$$\partial_t c = \nabla \cdot D_c \nabla c + F(c)$$

Scianna, Preziosi, Comp Biol Med, 2016

Scianna, Preziosi, Mult Mod Sim, 2012

Nested Cellular Potts Model

- Present topics:
 - cell migration in ECMs and microchannels
Scianna, Preziosi, Wolf, Math Biosci Eng, 2013
 - calcium signals and vascularization
Scianna, Munaron, Preziosi, Prog Biophys Mol Biol, 2011
 - reproduction of cell biophysical guidance mechanisms along muscle fibers
- **Perspectives:** Interface with continuous mechanics approaches for cell-substrate interactions



Hybrid Discrete-Continuous Models

- Individual/discrete cell

description:

- pointwise representation
- ODEs for cell dynamics

$$m \frac{d^2 \mathbf{x}_i}{dt^2} + \lambda_i \mathbf{v}_i + \sum_{j=1, j \neq i}^N \mu_{ij} (\mathbf{v}_i - \mathbf{v}_j) = \mathbf{F}_i$$

- Collective/continuous cell

description:

- use of cell densities
- balance laws for cell dynamics

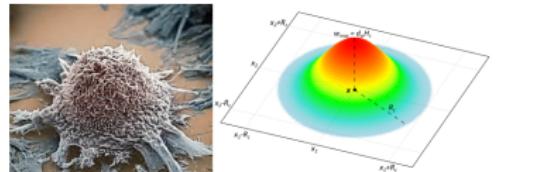
$$\partial_t \rho + \nabla \cdot (\rho \mathbf{v}_\rho) = \Gamma$$

$$\mathbf{v}_i = \sum_{j=1}^N \mathbf{K}(\mathbf{x}_i, \mathbf{x}_j) + \int_{\Omega} \mathbf{H}(\xi, \mathbf{x}_i) \rho(\xi) d\xi$$

- Derivation of integro-differential equations with non-local terms

- switches between cell representations via bubble-like functions or measure theory arguments

$$\mathbf{v}_\rho(\mathbf{y}) = \sum_{i=1}^N \mathbf{K}(\mathbf{x}_i, \mathbf{y}) + \int_{\Omega} \mathbf{H}(\xi, \mathbf{y}) \rho(\xi) d\xi$$



Hybrid Discrete-Continuous Models

- Present topics:

- inclusion of cell differentiation

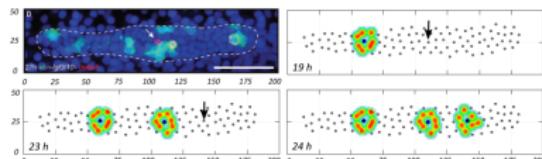
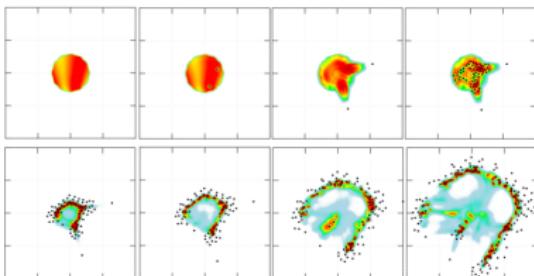
Colombi, Scianna, Tosin, J Math Biol, 2015

- description of tumor growth and invasion
- reproduction of zebrafish PLL formation

Colombi, Scianna, Preziosi, J Math Biol, 2017

- analysis of the H-stability of the system

Carrillo, Colombi, Scianna, J Theor Biol, 2018



- **Perspectives:** Derivation of efficient numerical tools to deal with singular intercellular interaction kernels

Kinetic description of multi-agent systems

(Vehicular traffic, pedestrian crowds, opinion dynamics)

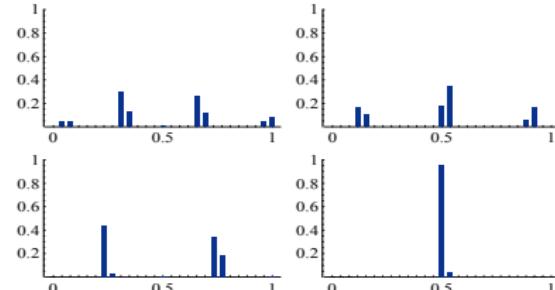
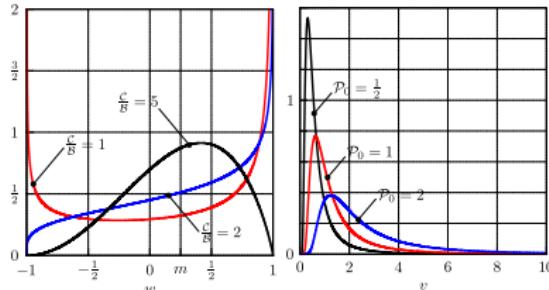
- Boltzmann-type integro-differential equations with or without space heterogeneity

$$\partial_t f + v \cdot \nabla_x f = \int_V \int_{\Omega} \left(\frac{1}{|J|} f(x, v') f(y, w') - f(x, v) f(y, w) \right) dy dw$$

- Statistical description of emerging aggregate trends
 - Kinetic limits and Fokker-Planck equations

$$\partial_t f + \partial_v \left(f(v) \int_V K(v, w) f(w) dw \right) = \sigma^2 \partial_v^2 (D^2(v) f)$$

- Asymptotic distributions, pattern formation, trends of statistical moments



Microscopic binary interactions

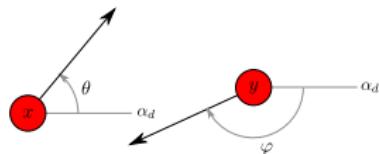
- Traffic: acceleration/deceleration

$$\begin{cases} v' = P(1 - v) + (1 - P)(Pw - v) + D(v)\eta \\ w' = w \end{cases}$$



- Crowds: collision avoidance

$$\begin{cases} \theta' = \theta + (1 - P(\theta, \varphi))(\alpha_d - \theta) + P(\theta, \varphi)\alpha_c \\ \varphi' = \varphi + (1 - P(\varphi, \theta))(\alpha_d - \varphi) + P(\varphi, \theta)\alpha_c \end{cases}$$



- Opinions: consensus/dissensus

$$\begin{cases} v' = v + \gamma(w - v) + D(v)\eta \\ w' = w + \gamma(v - w) + D(w)\eta \end{cases}$$

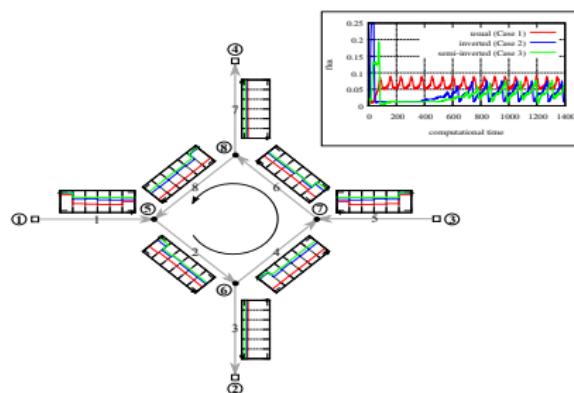


- Binary control problems

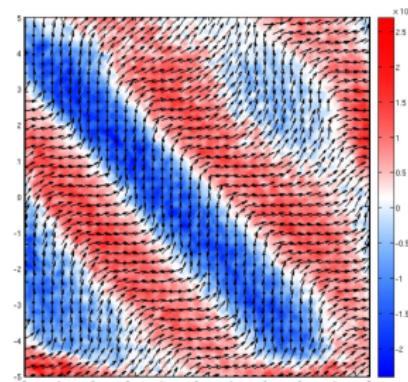
$$v' = v + \Delta t(l(v, w) + \textcolor{red}{u}) + D(v)\eta, \quad u^* = \arg \min_{u \in \mathcal{U}} \int_t^{t+\Delta t} \left(\langle R(v, w) \rangle + \frac{\nu}{2} u^2 \right) ds$$

Macroscopic trends

- Traffic flow on road networks



- Pedestrian counterflow



A. Festa, A. Tosin, M.-T. Wolfram, *Kinet. Relat. Models*, 2018

L. Fermo, A. Tosin, *Math. Models Methods Appl. Sci.*, 2015

- Hydrodynamics from non-Maxwellian closures

$$\begin{cases} \partial_t \rho + \partial_x (\rho(u - m)) = 0 \\ \partial_t (\rho(u - m)) + \partial_x \left(\rho \left((u - m)^2 + \frac{\lambda}{2+\lambda} (1 - u^2) \right) \right) = 0 \end{cases}$$

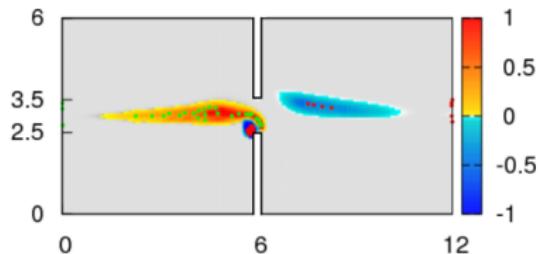
L. Pareschi, G. Toscani, A. Tosin, M. Zanella, *in preparation*

- Microscopically controlled equations at the macroscopic scale

A. Tosin, M. Zanella *in preparation*

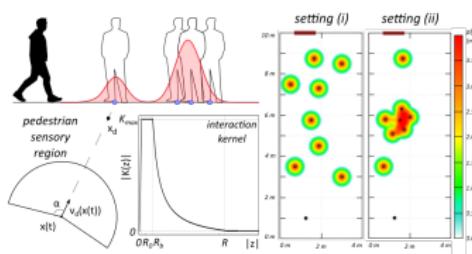
Hybrid discrete-continuous models

- Blended micro-macro description of 2D pedestrian flows



E. Cristiani, B. Piccoli, A. Tosin, *MS&A*, Springer, 2013

- Multiscale pedestrian perception in crowd dynamics



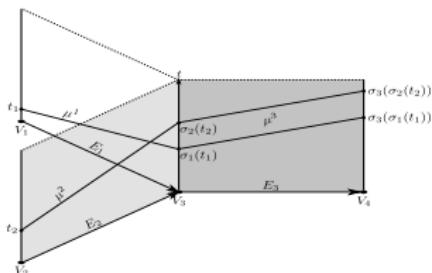
A. Colombi, M. Scianna, A. Tosin, *J. Coupled Syst. Multiscale Dyn.*, 2016

- Transport of measures

$$\mu_t = \gamma_t \# \mu_0, \quad \begin{cases} \dot{\gamma}_t(x) = v(\gamma_t(x)) \\ v(x) = v_d(x) + \int_{S(t)} K(y-x) d\mu_t(y) \end{cases}$$

Hybrid discrete-continuous models

- Blended micro-macro description of traffic flow on road networks

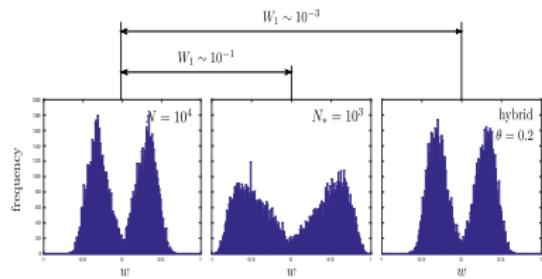


- Transport of measures on networks

$$\begin{cases} \partial_t \mu^j + \partial_x (\mu^j v_j[\mu^j]) = 0 \\ \mu_{t=0}^j = \mu_0^j \\ \mu_{V_i}^j = \sum_{k=1}^{d_i'} p_{kj}(t) \mu_{V_i}^k \end{cases}$$

F. Camilli, R. De Maio, A. Tosin, *J. Differential Equations*, 2018

- Multi-agent systems with symmetry breaking (opinion dynamics with polls)



- SDEs + Fokker-Planck equations

$$\begin{cases} dw_k &= [\theta K(w_k, \{w_h\}_{h=1}^N) \\ &\quad + (1-\theta)K[f](t, w_k)] dt \\ &\quad + \Theta dB_t^k \\ &\quad - (1-\Theta)D[f](t, w_k) dt \\ \partial_t f &= \partial_w ((D[f] - K[f])f) \end{cases}$$

E. Cristiani, A. Tosin, *Multiscale Model. Simul.*, 2018